

SAT-based Reasoning Techniques for LTL over Finite and Infinite Traces

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Linear Temporal Logic

- | First introduced to Computer Science by A. Pnueli in 1977
- | Formal verification (over infinite traces: LTL)
- | AI (over finite traces : LTL_f)

Linear Temporal Logic

Syntax for LTL and LTL_f

$$\phi ::= p \mid \neg \phi \mid \phi \wedge \psi \mid \phi \vee \psi \mid X\phi \mid \phi U \psi \mid \phi R \psi \mid G\phi \mid F\phi;$$

| $\phi U \psi = \neg \phi R \neg \psi$

| $X\phi = N:\phi$ (Weak Next), for LTL_f only

| $F\phi = \text{true} U \phi$

| $G\phi = \text{true} R \phi$

Linear Temporal Logic

Semantics for LTL (LTL_f),

- | Let ξ be a trace with $|\xi| = n$ ($n > 0$)
 - | $\xi \models p$ if $p \in \xi[0]$
 - | $\xi \models \neg \phi$ if $\xi \not\models \phi$
 - | $\xi \models \phi_1 \wedge \phi_2$ if $\xi \models \phi_1$ and $\xi \models \phi_2$
 - | $\xi \models X\phi$ if $n > 1$ and $\xi_1 \models \phi$
 - | $\xi \models \phi_1 U \phi_2$ if (1) there is $0 \leq i < n$ s.t. $\xi_i \models \phi_2$ and (2) for every $0 \leq j < i$ it holds $\xi_j \models \phi_1$.
- | LTL semantics: $n = /$
- | LTL_f semantics: $n < /$

LTL vs. LTL_f

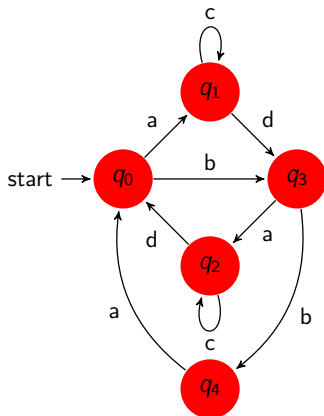
- | Xtt is always true in LTL, but not in LTL_f
- | $(a \wedge Xtt) \circlearrowleft a$ in LTL_f
- | $: X\phi \notin X:\phi$ ($: X\phi = N:\phi$)
- | $GX\phi$ is never satisfiable in LTL_f

This Talk

- | Present an on-the-fly approach to construct automata by SAT solvers
- | Show one of its applications to solve LTL_f satisfiability checking problem

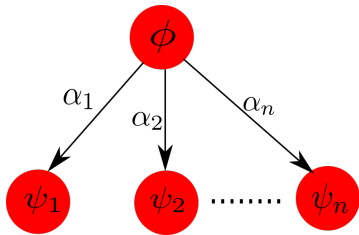
LTL(f) to Automata

$\phi \Rightarrow$



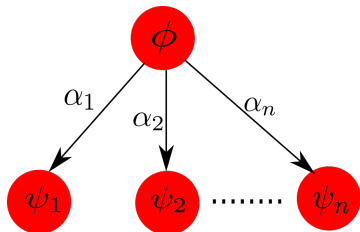
LTL(f) to Automata

$$\phi () \quad \forall_i(\alpha_i \wedge X(\psi_i))$$



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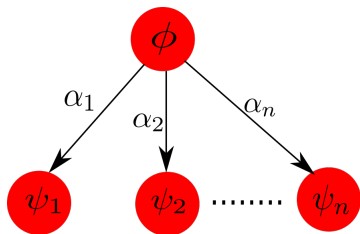
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Bottleneck: $\phi () \quad \forall_i (\alpha_i \wedge X(\psi_i))$ is expensive!

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Question: Is it possible to generate ONE successor at one time (on the fly)?

neXt Normal Form (XNF)

If considering the temporal subformulas as atoms, an $LTL(f)$ formula ϕ becomes a Boolean formula.

We say ϕ is in XNF iff only X/N subformulas can be its atom.

neXt Normal Form (XNF)

Example

| $(a _ bUc) \wedge cRd$ is not in XNF

| $(a _ c _ b \wedge X(bUc) \wedge d \wedge (c _ X(cRd)))$ is in XNF

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3. Take $xnf(\phi)$ as the input of a SAT solver

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3. Take $xnf(\phi)$ as the input of a SAT solver
4. SAT solver may return: $fa, : b, X(aUb), X(: bU: a)g$
 - | A transition in the automaton is $\phi^{a^{\wedge}!p} (aUb) \wedge (: bU: a)$

Invoking SAT solver

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4. SAT solver may return: $fa, : b, X(aUb), X(: bU: a)g$
 - | A transition in the automaton is $\phi \stackrel{a \wedge : b}{\rightarrow} (aUb) \wedge (: bU: a)$

To construct the whole automaton, just do enumeration!

LTL_f Satisfiability Checking

Problem

Given an LTL_f formula ϕ , is there a finite trace ξ s.t. $\xi \models \phi$?

- | Fa is satisfiable;
- | $Fa \wedge G: a$ is unsatisfiable;

Determining Final State

Introduce a new atom *Tail* to associate with *X*

$$X\psi \Rightarrow \text{Tail} \wedge X\psi$$

Example

- | $b_ X(aUb) \Rightarrow b_ : \text{Tail} \wedge X(aUb)$
- | $XX\phi \Rightarrow \text{Tail} \wedge X(: \text{Tail} \wedge X\phi)$

Determining Final State

Theorem

ϕ is a final state iff $Tail \wedge xnf(\phi)$ is satisfiable (Boolean formula).

BLSC: Basic SAT-based Checking

Algorithm 1 BLSC: Basic on-the-fly LTL_f Satisfiability Checking

Require: An LTL_f formula ϕ .

Ensure: SAT or UNSAT.

- 1: **if** $Tail \wedge xnf(\phi)$ is satisfiable **then**
 - 2: **return** SAT;
 - 3: **end if**
 - 4: Add ϕ into $block_list$;
 - 5: Let $\psi = xnf(\phi) \wedge X(block_list)$;
 - 6: **while** ψ is satisfiable **do**
 - 7: Let t be a propositional assignment for ψ ;
 - 8: Let $\phi^0 = \bigwedge f\theta jX\theta \geq tg$;
 - 9: **if** BLSC (ϕ^0) returns SAT **then**
 - 10: **return** SAT;
 - 11: **end if**
 - 12: **end while**
 - 13: **return** UNSAT;
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BLSC Overview

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- | Computing states via SAT solvers does not save the space!
- | Question: Can BLSC be improved?
 - | BLSC leverages the satisfiability from SAT solvers
 - | BLSC discards the unsatisfiability from SAT solvers

CDLSC: Conflict-Driven Checking

$Tail \wedge xnf(\phi)$ is UNSAT

\Rightarrow

there is ψ s.t. $\psi \models \phi^1$ and $Tail \wedge xnf(\psi)$ is still unsatisfiable
(UNSAT core)

¹Consider ϕ have the form of \bigwedge_i

CDLSC: Conflict-Driven Checking

$Tail \wedge xnf(\phi)$ is UNSAT

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there is ψ s.t. $\psi \models \phi^1$ and $Tail \wedge xnf(\psi)$ is still unsatisfiable
(UNSAT core)

- | ψ can be provided by a SAT solver
- | ψ represents a set of states that **cannot reach** a final state in 0 step

¹Consider $\phi = \bigwedge_i \phi_i$

CDLSC: Conflict-Driven Checking

Conflict Sequence: $C = C_0, C_1, C_2, \dots, C_k (k \geq 0)$

- | C_i : a set of states that **cannot reach** a final state in i steps

CDLSC: Conflict-Driven Checking

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- | C_i : a set of states that **cannot reach** a final state in i steps
- | Guided search:
 - | ψ is known in some $C_i \Rightarrow$ a next state of ψ not in C_i is preferred: $xf(\phi) \wedge \neg C_i$
 - | Otherwise, check final state: $Tail \wedge xf(\psi)$

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| Unsatisfiability check: $\bigcap_{0 \leq j < i} C_j \cap C_{i+1}$

Evaluation

- | Benchmarks: 7446 LTL-as- LTL_f formulas in previous work
- | Platform: Rice Davinci cluster
- | Timeout: 60 seconds for each instance
- | Tools:
 1. Aalta-finite [LZPVH14]
 2. Aalta-infinite [LZPV15]
 3. ltl2sat [FG16]
 4. nuXmv (IC3+KLIVE) [CCDGMMMRT14]
 5. BLSC
 6. CDLSC

Evaluation

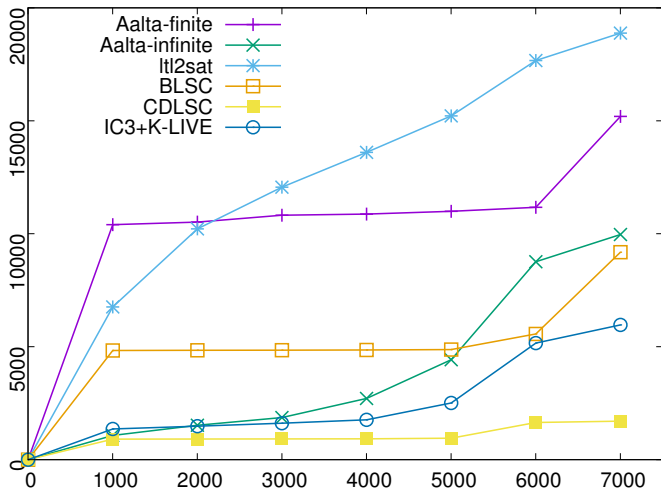


Figure 1: Cactus plot for LTL_f Satisfiability Checking on LTL-as- LTL_f Benchmarks.

Beyond Satisfiability Checking

- | On-the-fly Synthesis for LTL over finite traces [AAAI2019]
- | Satisfiability checking for LTL over infinite traces[FMSD 2019]
- | Synthesis for LTL over infinite traces?
- | On-the-fly LTL model checking?
- | Extension to word-level?

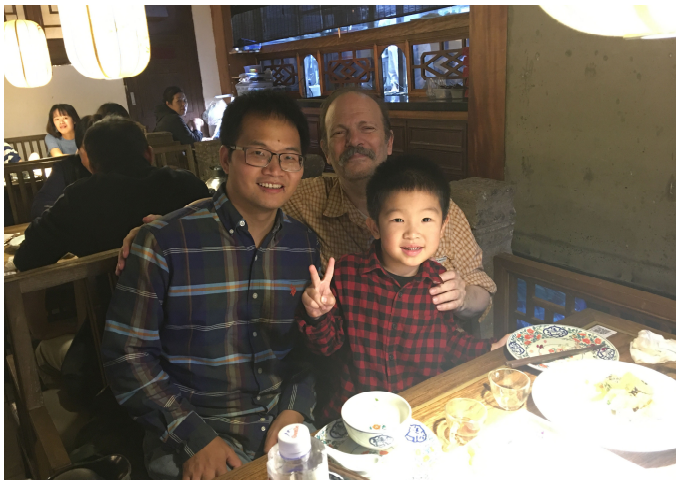


Figure 2: Shanghai, Oct. 2019.

Hope to see you again VERY soon!